

## Heat Capacities, Absolute Zero, and the Third Law

- We have already noted that heat capacity and entropy have the same units.
- We will explore further the relationship between heat capacity and entropy.
- We will see that entropy is absolute and explore the Third Law of Thermodynamics.

### Variation of Entropy with Temperature

- Consider:

$$dS = \frac{dq_{rev}}{T}$$

- We have considered constant  $V$  and constant  $P$  paths, respectively:

$$C_V = \frac{dq_V}{dT} = \left( \frac{\partial U}{\partial T} \right)_V$$

$$C_P = \frac{dq_P}{dT} = \left( \frac{\partial H}{\partial T} \right)_P$$

- Therefore

$$dS_V = \frac{C_V}{T} dT = \left( \frac{\partial S}{\partial T} \right)_V dT$$

$$dS_P = \frac{C_P}{T} dT = \left( \frac{\partial S}{\partial T} \right)_P dT$$

- Heat capacities are temperature dependent:

$$\Delta S_V = \int_{T_i}^{T_f} \frac{C_V(T)}{T} dT$$

$$\Delta S_P = \int_{T_i}^{T_f} \frac{C_P(T)}{T} dT$$

## Absolute Zero

- Consider 10 identical bricks beside a table of height  $h$ .
- If they are initially at  $h = 0$ , then the internal energy is  $U(n = 0)$ , where  $n$  is the number of bricks on the table.

- If  $n$  bricks are on the table, then the change in internal energy is:

$$\Delta U(n) = U(n) - U(n = 0) = nMgh = n\epsilon$$

where:

$$\epsilon = Mgh$$

- 1 way to have  $n = 0$ .
- 10 ways to have  $n = 1$ .
- 45 ways to have  $n = 2$ .
- $\vdots$
- $W(n)$  ways to have  $n = n$  where

$$W(n) = \frac{N!}{n!(N - n)!}$$

- Each specific arrangement is a microstate of the system.
- The entropy associated with the state of the system is:

$$S(n) = k_B \ln W(n)$$

- Therefore, the more microscopic states that correspond to a particular macrostate characterized by macroscopic variables (such as  $P$ ,  $V$ ,  $T$ ,  $U$ , and  $S$ ), the greater the entropy.

- Now split the set of ten bricks into two subsystems, each consisting of five bricks.
  - One set of bricks is on the table ( $U = 5\epsilon$ ).
  - One set of bricks is on the floor ( $U = 0$ ).
  - Bring the two systems together. Therefore  $U = 5\epsilon$ .
- But we still know which five bricks are on the table and which five are on the floor.
- Supposed that there existed an "interbrick force" by which bricks could trade places.
  - Therefore there will still be five bricks on the table and five bricks on the floor (and  $U = 5\epsilon$ ), but we no longer know which bricks are where.
- This is what happens with molecules. There is chaotic redistribution of molecules among microstates corresponding to the observed macrostate.
- Now consider molecules instead of bricks in the case where there are only two energy levels available for each molecule (i.e. a two level system).
  - The lower level has an energy of 0 and the higher level has an energy of  $\epsilon$ .

- Therefore, for the system:

$$\Delta U(n) = U(n) - U(n = 0) = n\epsilon$$

and

$$\Delta S(n) = S(n) - S(n = 0) = k_B \ln \left( \frac{N!}{n!(N - n)!} \right)$$

- Consider  $U(n)$  plotted against  $S(n)$  (Figure 4.2)
- Now remember the Master Equation:

$$dU = TdS - PdV$$

- Therefore:

$$\left( \frac{\partial(\Delta U(n))_V}{\partial(\Delta S(n))} \right)_V = \left( \frac{\partial U(n)}{\partial S(n)} \right)_V = T(n)$$

- Applying the chain rule:

$$\left( \frac{\partial U(n)}{\partial S(n)} \right)_V = \left( \frac{\partial U(n)}{\partial n} \right)_V \left( \frac{\partial n}{\partial S(n)} \right)_V$$

$$= \left( \frac{\partial U(n)}{\partial n} \right)_V \left( \frac{\partial S(n)}{\partial n} \right)_V^{-1}$$

- Since  $U(n) = n\epsilon$ ,  $(\partial U(n)/\partial n)_V = \epsilon$
- Now for  $(\partial S(n)/\partial n)_V$ :
  - Need to use Stirling's approximation for very large  $N$ :

$$\ln N! = N \ln N$$

- With Stirling's approximation:

$$\begin{aligned} \Delta S(n) &= k_B \ln \left( \frac{N!}{n!(N-n)!} \right) \\ &= k_B [\ln N! - \ln n! - \ln(N-n)!] \\ &\cong k_B [N \ln N - n \ln n - (N-n) \ln(N-n)] \end{aligned}$$

- we find:

$$\left( \frac{\partial S(n)}{\partial n} \right)_V = k_B \ln \left( \frac{N}{n} - 1 \right)$$

Therefore:

$$T(n) = \frac{\epsilon}{k_B \ln \left( \frac{N}{n} - 1 \right)}$$

**What is the limiting behaviour of this function?**

- If  $n \rightarrow 0$  then  $T(n) \rightarrow 0$ .
  - All the molecules are in their lowest state.
  - Internal energy at its lowest value.
  - Entropy at its lowest value.
- If  $n \rightarrow N/2$  then  $T(n) \rightarrow \infty$ 
  - Molecules evenly split between the two levels.
  - Entropy at its maximum value.
- Rearrange

$$T(n) = \frac{\epsilon}{k_B \ln \left( \frac{N}{n} - 1 \right)}$$

to

$$\ln \left( \frac{N}{n} - 1 \right) = \frac{\epsilon}{k_B T}$$

$$\ln \left( \frac{N - n}{n} \right) = \frac{\epsilon}{k_B T}$$

$$\ln \left( \frac{n}{N - n} \right) = -\frac{\epsilon}{k_B T}$$

$$\left( \frac{n}{N - n} \right) = e^{-\epsilon/k_B T}$$

(also known as the Boltzmann distribution)

- Consider the following two questions:
  - Are there real molecular systems with only two energy levels?
  - What about the dashed part of figure 4.2? If  $n > N/2$ , then the temperature would be negative!
- Consider a two level molecular systems:
  - For example, consider nuclear spin, which is either "up" or "down".
  - These levels are degenerate (i.e. have the same energy) if there is no external field.
  - If there is an external field, the energy levels are different.
  - Negative temperatures occur only in systems with very few energy levels.
  - Negative temperature systems are "hotter" than positive temperature systems associated with population inversions where the



higher energy state is more populated than the lower energy level.

- Population inversions are essential for the operation of lasers.
- It is  $1/T$  that characterizes the degree of "hotness".
  - $-1/T \rightarrow -\infty$  ( Coldest system)
  - $-1/T \rightarrow 0$
  - $-1/T \rightarrow \infty$  (Hottest system)

### More about heat capacity

- Recall:

$$T(n) = \frac{\epsilon}{k_B \ln \left( \frac{N}{n} - 1 \right)}$$

- which was rearranged to:

$$\left( \frac{n}{N - n} \right) = e^{-\epsilon/k_B T}$$

- Solving for n gives:

$$n = N \frac{e^{-\epsilon/k_B T}}{1 + e^{-\epsilon/k_B T}} = N \frac{e^{-x}}{1 + e^{-x}}$$

where  $x = \epsilon/k_B T$ .

- Therefore:

$$U(T) = n\epsilon = N\epsilon \frac{e^{-x}}{1 + e^{-x}}$$

and

$$C_V = \left( \frac{\partial U(T)}{\partial T} \right)_V = Nk_B x^2 \frac{e^{-x}}{(1 + e^{-x})^2}$$

- Figure 4.4 shows heat capacity as a function of temperature.
- Heat capacity increases then decreases.
- Once a molecule is in the upper of the two states, how can it be further excited?
- Real molecules have many states.
  - Therefore heat capacity increases with temperature.
  - As temperature increases more energy levels (and other types of energy levels) become available.

## Heat Capacity of Solids

- Dulong and Petit (1819) observed that  $\overline{C}_V$  for atomic solids was independent of temperature and was approximately the same for a wide range of atomic solids.

$$\overline{C}_V = 3R$$

- This can be interpreted in terms of the vibrations of the atoms within the atomic crystal with each direction ( $x, y, z$  contributing  $R$  to the molar heat capacity.
- Kopp (1865) devised an empirical scheme for estimating heat capacities of polyatomic solids with the contribution of each atom empirically determined (Table 4.1).
  - The values for  $\overline{C}_V$  range from  $0.9R$  for a carbon atom to  $3.02R$  for other atoms. It works reasonably well.
- How does heat capacity vary with temperature as  $T \rightarrow 0$ ?

## Heat Capacity at Low Temperatures

- Recall that the temperature dependence of heat capacity depends roughly on the magnitude of  $k_B T$  relative to the spacing of quantum levels.
  - If the spacing is “too big” that degree of freedom is not “active” at that temperature.
  - Therefore we hypothesize that heat capacity approaches zero as  $T$  approaches zero.
- Debye (1912) modified Einstein’s theory (1907).
  - Debye’s Law is:

$$\frac{\overline{C}_V}{R} = \frac{12\pi^4}{5} \left( \frac{T}{\Theta_D} \right)^3$$

where  $\Theta_D$  is the Debye temperature.

- The Debye temperature is related to nuclear motions in the solid and thus the nature of the metal with soft metals having lower  $\Theta_D$  than harder metals.
- Electronic states also can contribute to the heat capacity of a metal, but in a different way than do nuclear motions.

- For electrons:

$$\frac{\overline{C}_V}{R} = \frac{T}{\Theta_{el}}$$

- Thus the total heat capacity of a metal is:

$$\frac{\overline{C}_V}{R} = \frac{T}{\Theta_{el}} + \frac{12\pi^4}{5} \left( \frac{T}{\Theta_D} \right)^3$$

## Heat Capacity of Liquids

- In a liquid the molecules are no longer constrained to motion about one particular site.
- Therefore the heat capacity of a liquid is greater than the heat capacity of a solid.
- The heat capacity of a liquid is also greater than that of a gas because of the proximity of the molecules to each other.
- Heat capacities of liquids are empirically determined and are typically around  $9R$  for small molecules.
  - For larger molecules, internal degrees of freedom must be considered and the heat capacity is larger.

## Heat Capacity of Gases

- Depends on internal structure of the gas.
- If there are  $N$  atoms in the gas there are:
  - Three translational degrees of freedom, each contributing  $R/2$  to  $C_V$ .
- If the molecule is linear, then there are:
  - 2 rotational degrees of freedom, each contributing  $R/2$  to  $C_V$ .
  - $3N - 5$  vibrational degrees of freedom, each contributing  $R$  to  $C_V$ .
- If the molecule is nonlinear, then there are:
  - 3 rotational degrees of freedom, each contributing  $R/2$  to  $C_V$ .
  - $3N - 6$  vibrational degrees of freedom, each contributing  $R$  to  $C_V$ .
- This is assuming all degrees of freedom are active.
- Heat capacity for gases is determined empirically and is usually expressed as:

$$\frac{C_p(T)}{R} = a + bT + cT^2 + dT^3$$

- We must now consider the relationship between  $C_V$  and  $C_P$ .
  - Recall

$$C_P - C_V = \left( \frac{\partial U}{\partial V} \right)_T \left( \frac{\partial V}{\partial T} \right)_P + P \left( \frac{\partial V}{\partial T} \right)_P$$

which leads to:

$$\overline{C}_P - \overline{C}_V = \frac{TV\alpha^2}{\kappa}$$

where

$$\alpha \equiv \frac{1}{V} \left( \frac{\partial V}{\partial T} \right)_P$$

and

$$\kappa \equiv -\frac{1}{V} \left( \frac{\partial V}{\partial P} \right)_T$$

- In the adiabatic expansion, we encountered the ratio  $\gamma$  .
  - For an ideal gas  $\gamma = 5/3$ .
- Without using the ideal gas equation of state, it can be shown that  $\gamma = C_P/C_V$ .

- Assuming that  $C_P - C_V = nR$ ,  $\gamma$  for a polyatomic molecule can indicate the number of atoms and whether the molecule is linear.

- For a monatomic gas:

$$\gamma = \frac{5}{3}$$

- For a linear molecule in the gas phase:

$$\frac{7}{5} \geq \gamma \geq \frac{6N - 3}{6N - 5}$$

- For a nonlinear molecule in the gas phase:

$$\frac{4}{3} \geq \gamma \geq \frac{6N - 4}{6N - 6}$$

- The relationship

$$\overline{C}_P - \overline{C}_V = \frac{TV\alpha^2}{\kappa}$$

is important for condensed phases.

- $\alpha$  is  $T$  dependent for both solids and liquids. Typical values are approximately  $10^{-5} \text{ K}^{-1}$  for solids and  $10^{-3}$  to  $10^{-4} \text{ K}^{-1}$  for liquids.
- $\kappa$  is not strongly  $T$  dependent for and is about  $10^{-6} \text{ atm}^{-1}$  for metals and  $10^{-4} \text{ atm}^{-1}$  for molecular solids.



- Recall

$$\left(\frac{\partial U}{\partial V}\right)_T = T \left(\frac{\partial P}{\partial T}\right)_V - P$$

- Since  $U$  is a state function, it has an exact differential.

- Therefore:

$$\frac{\partial}{\partial V} \left(\frac{\partial U}{\partial T}\right) = \frac{\partial}{\partial T} \left(\frac{\partial U}{\partial V}\right)$$

- But:

$$\left(\frac{\partial U}{\partial T}\right)_V = C_V$$

and:

$$\frac{\partial}{\partial T} \left(\frac{\partial U}{\partial V}\right) = \frac{\partial}{\partial T} \left[ T \left(\frac{\partial P}{\partial T}\right)_V - P \right]$$

$$= T \left(\frac{\partial^2 P}{\partial T^2}\right)_V$$

$$\left(\frac{\partial C_V}{\partial V}\right)_T = T \left(\frac{\partial^2 P}{\partial T^2}\right)_V$$

- Following the same procedure, but starting with  $H$  it may be shown that:

$$\left(\frac{\partial C_P}{\partial P}\right)_T = -T \left(\frac{\partial^2 V}{\partial T^2}\right)_P$$

- We have now considered the heat capacity of solids, liquids, and gases.
- We already know how to calculate entropy changes from heat capacity.
- In order to calculate absolute entropy starting from absolute zero to the temperature of interest, we must now consider the entropy of phase changes.

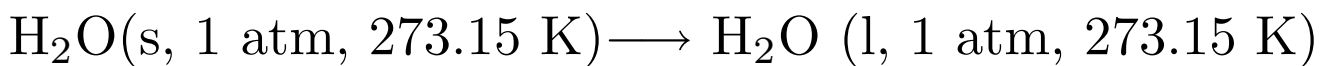
## Phase Transitions

- Some common phase transitions are:
- Solid to solid, i.e. from one crystalline state to another
  - $\text{H}_2\text{O}$  ice I to ice II
  - rhombic S to monoclinic S
  - Fe phase 1 and Fe phase 2
- Solid to liquid (fusion)
- Solid to gas (sublimation)
- Liquid to gas (vaporization)

- During a phase transition, heat is transferred into or out of the system without changing the temperature.
  - Since constant  $P$  conditions are more easily maintained than constant  $V$  conditions,  $q_P$ , is usually measured.

## Fusion of water

- Consider one mole of ice at 273.15 K and 1 atm.
- Transfer energy until ice melts leaving one mole of water.



- The associated heat transfer is:

$$q = q_P = \Delta \bar{H} = \Delta \bar{H}(\text{water}) - \bar{H}(\text{ice})$$

which is the enthalpy change of fusion,  $\Delta \bar{H}_{fus}$ , (also known as the heat of fusion).

- The standard enthalpy of fusion,  $\Delta \bar{H}_{fus}^\circ$ , is defined with respect to the pressure of 1 bar (**not 1 atm**).
- Similarly defined is the standard enthalpy of vaporization,  $\Delta \bar{H}_{vap}^\circ$ .

- For a given substance,  $\Delta\overline{H}_{vap}^\circ$  is usually greater than  $\Delta\overline{H}_{fus}^\circ$ .
  - This is because fusion involves partially overcoming intermolecular interactions while vaporization involves completely overcoming intermolecular interactions.
- If a substance goes directly from the solid to the gas phase, the process is called sublimation and  $\Delta\overline{H}_{sub}^\circ$  is the corresponding standard enthalpy.
- There are also solid-solid phase transitions between different solid crystalline forms.
  - Associated standard enthalpies tend to be small.

## Entropy of Phase Transitions

- During a phase transition at constant  $T$  and  $P$ , both phases are in equilibrium with each other.
  - For a general phase transition,  $\phi$ ,

$$\Delta S_\phi = \frac{q_\phi}{T_\phi} = \frac{\Delta H_\phi}{T_\phi}$$

- Standard entropies of phase transitions for water are:

$$\Delta S_{vap}^{\circ} = \frac{\Delta H_{vap}^{\circ}}{T_{vap}} = 13.10R$$

$$\Delta S_{fus}^{\circ} = \frac{\Delta H_{fus}^{\circ}}{T_{fus}} = 2.65R$$

## The Third Law and Absolute Entropy

- Absolute entropy can be assigned to any state.
  - Recall the bricks and the microstate where all the bricks were on the floor (or  $n = 0$ ).

$$W(n = 0) = \frac{N!}{0!N!} = 1$$

- Therefore:

$$S(n = 0) = k_B \ln W(n = 0) = 0$$

- Since the definition of  $W$  does not involve a reference state, the corresponding entropy is absolute.
- For a molecular system, all the bricks on the floor would correspond to the molecules arranged in a perfect crystal.

## Statements of the Third Law

- "At absolute zero, the entropy of every perfect crystalline equilibrium compound is zero."
- "The entropy of any equilibrium system is zero for the state in which  $(\partial U/\partial S)_V = 0$ ."
- "The isotherm  $T = 0$  and the isentrope  $S = 0$  are the same."
- "It is impossible to attain absolute zero by any process with a finite number of steps."
- Therefore it is impossible to reach absolute zero.

## Calculation of Absolute Entropy

- Consider entropy:

$$dS_V = \frac{C_V(T)}{T} dT$$

$$dS_P = \frac{C_P(T)}{T} dT$$

- Consider the entropy change at constant pressure from  $T_i$  and  $T_f$ :

$$\Delta S = S(T_f) - S(T_i) = \int_{T_i}^{T_f} \frac{C_P(T)}{T} dT$$

- This would be fine if there were no phase transitions.
  - Entropy changes due to phase changes must be explicitly considered.
- If the change from  $T_i$  and  $T_f$  involves a phase transition from phase I to phase II at  $T_\phi$ :

$$\Delta S = S(T_f) - S(T_i)$$

$$= \int_{T_i}^{T_\phi} \frac{C_P^I(T)}{T} dT + \frac{\Delta H_\phi}{T_\phi} + \int_{T_\phi}^{T_f} \frac{C_P^{II}(T)}{T} dT$$

- If  $T_i = 0$  and every phase transition is considered, absolute entropy of any pure substance at any temperature may be determined.
- Your text works an example for  $O_2$ .

**Here ends Chapter 4**